

电动力学学习题课

第三章 静磁场

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第三章作业

- ▶ 教材 P79 例题 1; 第三章习题 1, 4-7, 9, 10, 13.

3.4 (无穷长线电流)

- ▶ 直角坐标系 (x, y, z) 和柱坐标系 (r, ϕ, z) ; $(x < 0)$: 介质, \mathbf{B}_1 ; $(x > 0)$: 真空, \mathbf{B}_2
- ▶ 对于以原点为圆心、半径为 r 的圆形环路, 根据安培环路定理:

$$\int_{L_1} \mathbf{H} \cdot d\boldsymbol{\ell} + \int_{L_2} \mathbf{H} \cdot d\boldsymbol{\ell} = I$$

- ▶ 边界 $(x = 0)$ 条件: $B_{1x} = B_{2x}$, $\hat{\mathbf{x}} \times (\mathbf{H}_2 - \mathbf{H}_1) = 0$

$$\mathbf{B}_1 = \mathbf{B}_2 = \frac{\mu\mu_0}{\mu + \mu_0} \frac{I}{\pi r} \hat{\boldsymbol{\phi}}$$

$$\mathbf{H}_1 = \frac{1}{\mu} \mathbf{B}_1, \quad \mathbf{H}_2 = \frac{1}{\mu_0} \mathbf{B}_2$$

- ▶ $r = 0$: $\mathbf{H}_1, \mathbf{H}_2 \rightarrow \infty$; $r \rightarrow \infty$: $\mathbf{H}_1, \mathbf{H}_2 \rightarrow 0$
- ▶ 磁化强度和磁化电流: $\mathbf{M}_1 = (\mu/\mu_0 - 1)\mathbf{H}_1$, $\mathbf{M}_2 = 0$, 磁化线电流 (在电流 I 与介质分界面处):

$$I_M = \oint \mathbf{M} \cdot d\boldsymbol{\ell} = \int \mathbf{M}_1 \cdot d\boldsymbol{\ell} = \frac{\mu - \mu_0}{\mu + \mu_0} I$$

3.5 (磁场无源性)

- ▶ 轴对称磁场 ($\partial B_\phi / \partial \phi = 0$), 已知在原点附近的磁场 z 分量, 求 r 分量

$$\nabla \cdot \mathbf{B} = \frac{1}{r} \frac{\partial}{\partial r}(rB_r) + \frac{1}{r} \frac{\partial B_\phi}{\partial \phi} + \frac{\partial B_z}{\partial z} = \frac{1}{r} \frac{\partial}{\partial r}(rB_r) - 2Cz = 0$$

由此可得 $B_r = Czr$.

3.7 (均匀电流圆柱导体的磁矢势)

- ▶ $\mathbf{A} \propto \int \mathbf{J}/r \, dV'$, 由 \mathbf{J} 只有 z 分量可得 \mathbf{A} 只有 z 分量。
- ▶ 定解问题:
 - ▶ $\nabla^2 \mathbf{A}_1 = -\mu_0 \mathbf{J} \hat{z} \quad (r < a); \quad \nabla^2 \mathbf{A}_2 = 0 \quad (r > a)$
 - ▶ $r = 0, \mathbf{A}_1$ 有限
 - ▶ 边界条件: $r = a: \mathbf{A}_1 = \mathbf{A}_2 = 0, \hat{\mathbf{r}} \times \left(\frac{1}{\mu} \nabla \times \mathbf{A}_2 - \frac{1}{\mu_0} \nabla \times \mathbf{A}_1 \right) = 0$
- ▶ 从电流分布的对称性可得 $\mathbf{A}_1 = A_1 \hat{z} = A_1(r) \hat{z}$, 由边界条件可得外部矢势 $\mathbf{A}_2 = A_2(r) \hat{z}$, 由此可得

$$\frac{1}{r} \frac{d}{dr} \left(r \frac{dA_1}{dr} \right) = -\mu_0 J, \quad \frac{1}{r} \frac{d}{dr} \left(r \frac{dA_2}{dr} \right) = 0$$

解得 (积分常数由边界条件确定)

$$\mathbf{A}_1 = \frac{\mu_0}{4} (a^2 - r^2) \mathbf{J}, \quad \mathbf{A}_2 = \frac{\mu_0 a^2}{2} \ln \frac{a}{r} \mathbf{J}.$$

3.9 (均匀介质球在均匀外磁场中的磁化)

▶ 没有自由电流, 可以采用磁标势求解 (类似于静电势)

▶ 定解问题:

$$\text{▶ } \nabla^2 \varphi_1 = 0 \quad (R < R_0); \quad \nabla^2 \varphi_2 = 0 \quad (R > R_0)$$

$$\text{▶ } R = 0, \varphi_1 \text{ 有限}; \quad R \rightarrow \infty, \varphi_2 \rightarrow -H_0 R \cos \theta$$

$$\text{▶ 边界条件: } R = R_0, \varphi_1 = \varphi_2, \mu \frac{\partial \varphi_1}{\partial R} = \mu_0 \frac{\partial \varphi_2}{\partial R} .$$

▶ 通解:

$$\varphi_1 = \sum_n a_n R^n P_n, \quad \varphi_2 = -H_0 R P_1 + \sum_n \frac{b_n}{R^{n+1}} P_n$$

▶ 带入边界条件解出各系数, 结果为:

$$\varphi_1 = -\frac{3\mu_0}{\mu + 2\mu_0} \mathbf{H}_0 \cdot \mathbf{R}, \quad \varphi_2 = -\mathbf{H}_0 \cdot \mathbf{R} + \frac{(\mu - \mu_0)R_0^3}{(\mu + 2\mu_0)R^3} \mathbf{H}_0 \cdot \mathbf{R}$$

3.10 (均匀介质空心球的磁屏蔽作用)

- ▶ 没有自由电流，可以采用磁标势求解（类似于静电势）
- ▶ 定解问题：

$$\varphi_1 = \sum_n a_n R^n P_n \quad (R < R_1)$$

$$\varphi_2 = \sum_n \left(b_n R^n + \frac{c_n}{R^{n+1}} \right) P_n \quad (R_1 < R < R_2)$$

$$\varphi_3 = -H_0 R \cos \theta + \sum_n \frac{d_n}{R^{n+1}} P_n \quad (R > R_3)$$

- ▶ 边界条件：

$$R = R_1 : \quad \varphi_1 = \varphi_2, \quad \mu_0 \frac{\partial \varphi_1}{\partial R} = \mu \frac{\partial \varphi_2}{\partial R}$$

$$R = R_2 : \quad \varphi_2 = \varphi_3, \quad \mu \frac{\partial \varphi_2}{\partial R} = \mu_0 \frac{\partial \varphi_3}{\partial R} .$$

3.10 (均匀介质球壳的磁屏蔽作用)

- ▶ 解得空腔内的标势 φ_1 和磁场为

$$\varphi_1 = a_1 R \cos \theta, \quad \mathbf{B}_1 = -\mu_0 \nabla \varphi_1 = -\mu_0 a_1 \hat{\mathbf{z}},$$

其中

$$a_1 = -H_0 \times \left\{ \frac{2(\mu - \mu_0)^2}{9\mu\mu_0} \left[\frac{(\mu + 2\mu_0)(2\mu + \mu_0)}{2(\mu - \mu_0)^2} - \left(\frac{R_1}{R_2} \right)^3 \right] \right\}^{-1}$$

介质的磁导率 μ 越大, a_1 越弱, \mathbf{B}_1 越弱, 球壳对外磁场的屏蔽作用越显著。

3.13 (匀速转动的均匀带电薄球壳的磁场)

- ▶ David Griffiths, *Introduction to Electrodynamics*, the 4th edition, P245, Example 5.11

It might seem natural to set the polar axis along $\boldsymbol{\omega}$, but in fact the integration is easier if we let \mathbf{r} lie on the z axis, so that $\boldsymbol{\omega}$ is tilted at an angle ψ . We may as well orient the x axis so that $\boldsymbol{\omega}$ lies in the xz plane, as shown in Fig. 5.46. According to Eq. 5.66,

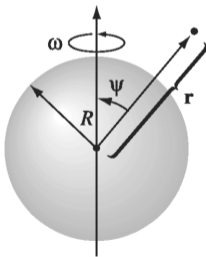


FIGURE 5.45

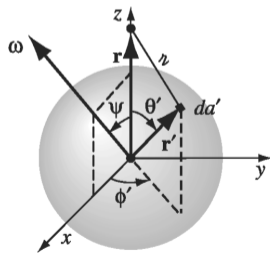


FIGURE 5.46

3.13 (匀速转动的均匀带电薄球壳的磁场)

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{K}(\mathbf{r}')}{r} da',$$

where $\mathbf{K} = \sigma \mathbf{v}$, $r = \sqrt{R^2 + r^2 - 2Rr \cos \theta'}$, and $da' = R^2 \sin \theta' d\theta' d\phi'$. Now the velocity of a point \mathbf{r}' in a rotating rigid body is given by $\boldsymbol{\omega} \times \mathbf{r}'$; in this case,

$$\begin{aligned} \mathbf{v} = \boldsymbol{\omega} \times \mathbf{r}' &= \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \omega \sin \psi & 0 & \omega \cos \psi \\ R \sin \theta' \cos \phi' & R \sin \theta' \sin \phi' & R \cos \theta' \end{vmatrix} \\ &= R\omega [-(\cos \psi \sin \theta' \sin \phi') \hat{\mathbf{x}} + (\cos \psi \sin \theta' \cos \phi' - \sin \psi \cos \theta') \hat{\mathbf{y}} \\ &\quad + (\sin \psi \sin \theta' \sin \phi') \hat{\mathbf{z}}]. \end{aligned}$$

Notice that each of these terms, save one, involves either $\sin \phi'$ or $\cos \phi'$. Since

$$\int_0^{2\pi} \sin \phi' d\phi' = \int_0^{2\pi} \cos \phi' d\phi' = 0,$$

such terms contribute nothing. There remains

$$\mathbf{A}(\mathbf{r}) = -\frac{\mu_0 R^3 \sigma \omega \sin \psi}{2} \left(\int_0^\pi \frac{\cos \theta' \sin \theta'}{\sqrt{R^2 + r^2 - 2Rr \cos \theta'}} d\theta' \right) \hat{\mathbf{y}}.$$

3.13 (匀速转动的均匀带电薄球壳的磁场)

Letting $u \equiv \cos \theta'$, the integral becomes

$$\begin{aligned} \int_{-1}^{+1} \frac{u}{\sqrt{R^2 + r^2 - 2Rru}} du &= -\frac{(R^2 + r^2 + Rru)}{3R^2r^2} \sqrt{R^2 + r^2 - 2Rru} \Big|_{-1}^{+1} \\ &= -\frac{1}{3R^2r^2} [(R^2 + r^2 + Rr)|R - r| \\ &\quad - (R^2 + r^2 - Rr)(R + r)]. \end{aligned}$$

If the point \mathbf{r} lies *inside* the sphere, then $R > r$, and this expression reduces to $(2r/3R^2)$; if \mathbf{r} lies *outside* the sphere, so that $R < r$, it reduces to $(2R/3r^2)$. Noting that $(\boldsymbol{\omega} \times \mathbf{r}) = -\omega r \sin \psi \hat{\mathbf{y}}$, we have, finally,

$$\mathbf{A}(\mathbf{r}) = \begin{cases} \frac{\mu_0 R \sigma}{3} (\boldsymbol{\omega} \times \mathbf{r}), & \text{for points } \textit{inside} \text{ the sphere,} \\ \frac{\mu_0 R^4 \sigma}{3r^3} (\boldsymbol{\omega} \times \mathbf{r}), & \text{for points } \textit{outside} \text{ the sphere.} \end{cases} \quad (5.68)$$

Having evaluated the integral, I revert to the “natural” coordinates of Fig. 5.45, in which $\boldsymbol{\omega}$ coincides with the z axis and the point \mathbf{r} is at (r, θ, ϕ) :

$$\mathbf{A}(r, \theta, \phi) = \begin{cases} \frac{\mu_0 R \omega \sigma}{3} r \sin \theta \hat{\boldsymbol{\phi}}, & (r \leq R), \\ \frac{\mu_0 R^4 \omega \sigma}{3} \frac{\sin \theta}{r^2} \hat{\boldsymbol{\phi}}, & (r \geq R). \end{cases} \quad (5.69)$$

3.13 (匀速转动的均匀带电薄球壳的磁场)

Curiously, the field inside this spherical shell is *uniform*:

$$\mathbf{B} = \nabla \times \mathbf{A} = \frac{2\mu_0 R \omega \sigma}{3} (\cos \theta \hat{\mathbf{r}} - \sin \theta \hat{\boldsymbol{\theta}}) = \frac{2}{3} \mu_0 \sigma R \omega \hat{\mathbf{z}} = \frac{2}{3} \mu_0 \sigma R \boldsymbol{\omega}. \quad (5.70)$$